

THERMODYNAMICS OF MULTIPARTITE PROCESSES WITH CONSTRAINTS ON RATE MATRIX DEPENDENCIES

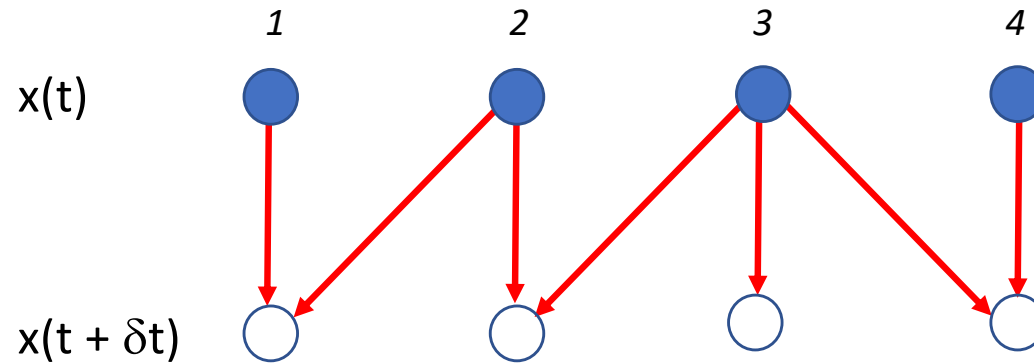
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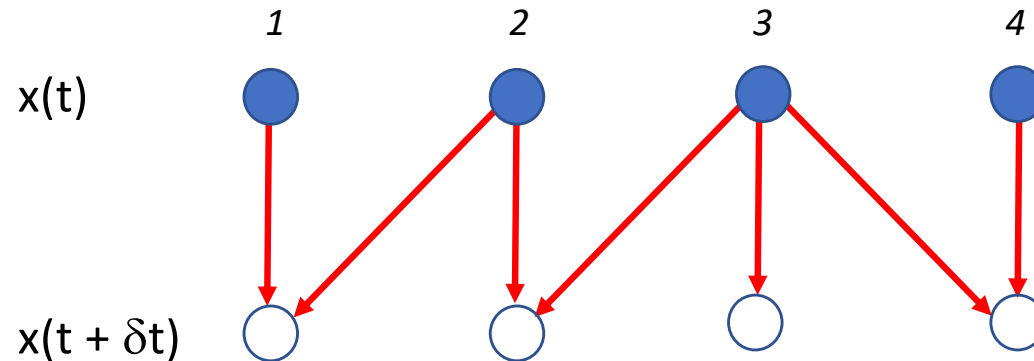


Example of a multipartite process



- Four subsystems, $\{1, 2, 3, 4\}$
- Red arrows indicate the dependencies of their rate matrices
- N.b., $\{3\}$ evolves independently, but is observed by $\{2\}$ and $\{4\}$
- So $\{2\}$ and $\{4\}$ are not physically coupled, but become statistically coupled with time

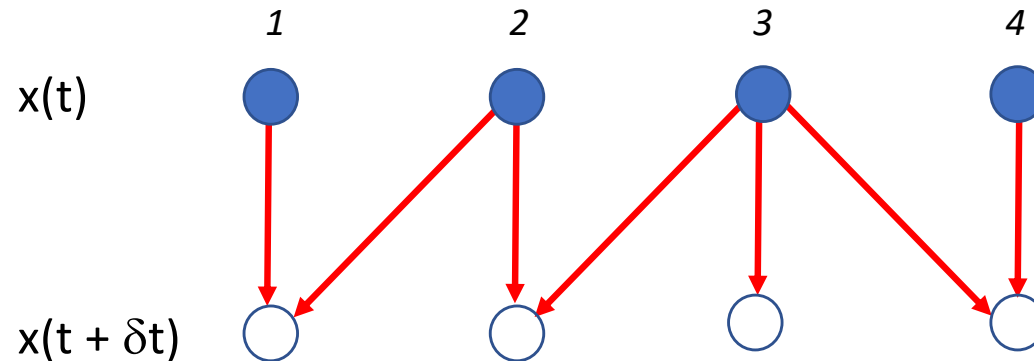
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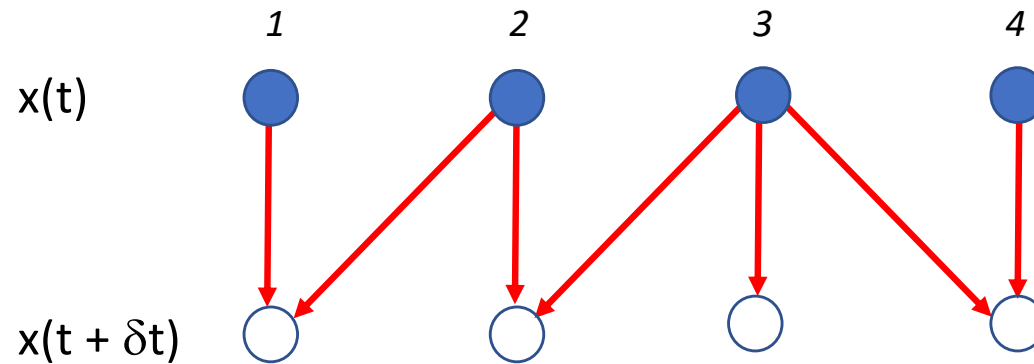
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How does minimal entropy production (EP) rate depend on red arrow graph?
How are EP fluctuations of the subsystems coupled?

This talk



- 1) **Trajectory-level thermodynamics of multipartite processes**
- 2) First decomposition of system-wide EP in terms of subsystem properties and an information-theoretic property of “red arrow graph”
- 3) Resultant lower bounds on expected EP rate in terms of red arrow graph
- 4) Second decomposition of system-wide EP in terms of subsystem properties and an information-theoretic property of “red arrow graph”
- 5) Resultant “vector” fluctuation theorem in terms of red arrow graph



N – set of subsystems

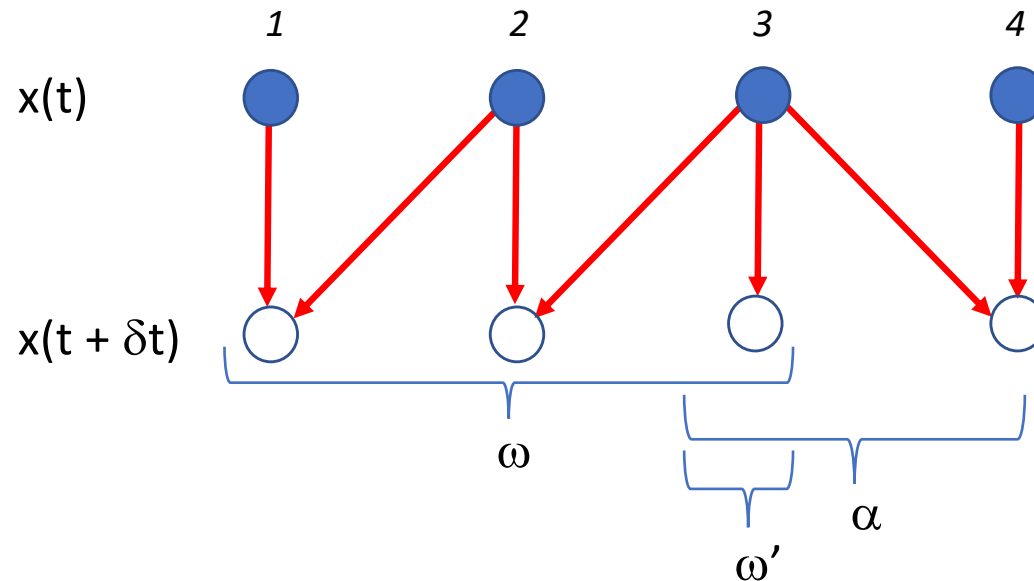
\mathbf{x} – joint state of all subsystems

$\mathbf{x}_i(t)$ – state of subsystem i at time t

Since it's a multipartite process:

$$\frac{dp_x(t)}{dt} = \sum_{x'} \sum_{i \in N} K_x^{x'}(i; t) p_{x'}(t)$$

$$\forall x, x' : x_{-i} \neq x'_{-i}, K_x^{x'}(i; t) = 0$$

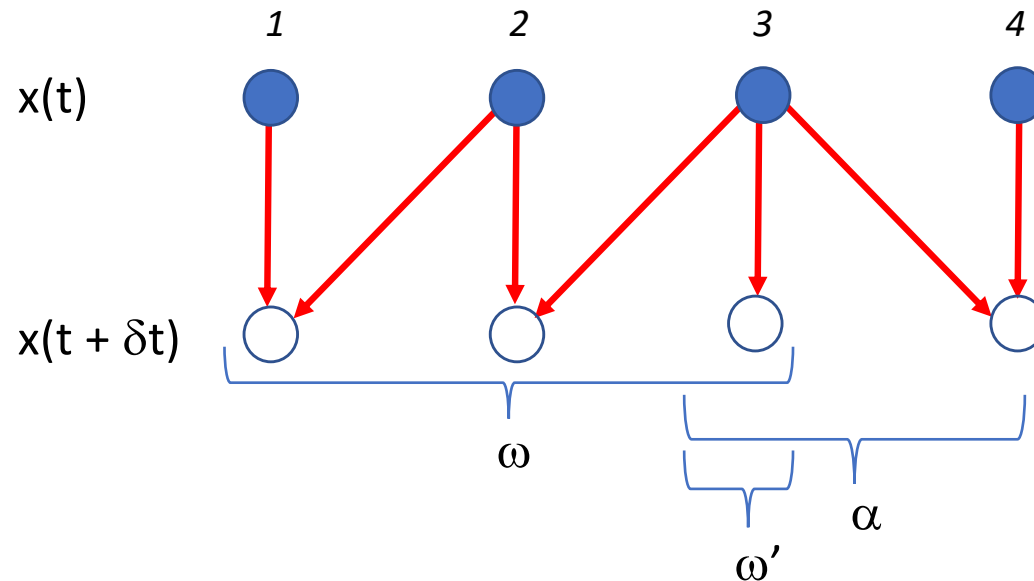


$$\frac{dp_x(t)}{dt} = \sum_{x'} \sum_{i \in N} K_x^{x'}(i; t) p_{x'}(t)$$

- A **community** r is a set of subsystems such that for every $i \in r$, $K(i; t)$ depends only on other subsystems $j \in r$:

$$K_x^{x'}(i; t) = K_{x_r}^{x'_r}(i; t) \delta(x'_{-r}, x_{-r})$$

- Dynamics of \mathbf{x}_r depends only on \mathbf{x}_r ; communities are “self-contained”



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- A **community structure** is a set of communities, closed under intersection, that covers N

Subsystem local detailed balance (SLDB)

Each subsystem is in contact with its own heat reservoirs:

$$\frac{K_{x_r}^{x'_r}(i; k, t)}{K_{x'_r}^{x_r}(i; k, t)} = \beta_i^k [H_{x'_r}(i; t) - H_{x_r}(i; t)]$$

for all i, k, t where

- r is a community containing subsystem i
- k is a heat reservoir
- $H_{x_r}(i; t)$ is **local Hamiltonian** of subsystem i

(Can be extended to include particle reservoirs)

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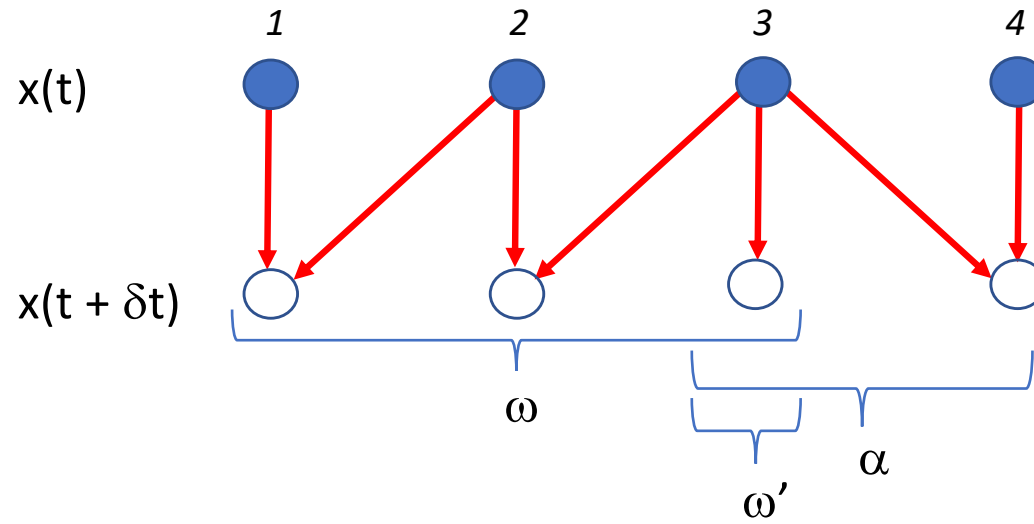
- r is a community containing subsystem i
- k is a heat reservoir
- $H_{x_r}(i; t)$ is **local Hamiltonian** of subsystem i

(Can be extended to include particle reservoirs)

-
- Therefore **local heat flow** into subsystem i during trajectory \mathbf{x} is

$$Q^i(\mathbf{x}) = \sum_{\mathbf{j}} \beta_{\mathbf{i}}^{\mathbf{k}(\mathbf{j})} [\mathbf{H}_{\mathbf{x}_r(\tau(\mathbf{j}))}(\mathbf{i}; \tau(\mathbf{j})) - \mathbf{H}_{\mathbf{x}_r(\tau(\mathbf{j}-1))}(\mathbf{i}; \tau(\mathbf{j}))]$$

where $\mathbf{x}_r(\tau(\mathbf{j}))$ is community r 's state at j 'th time that subsystem i changes state

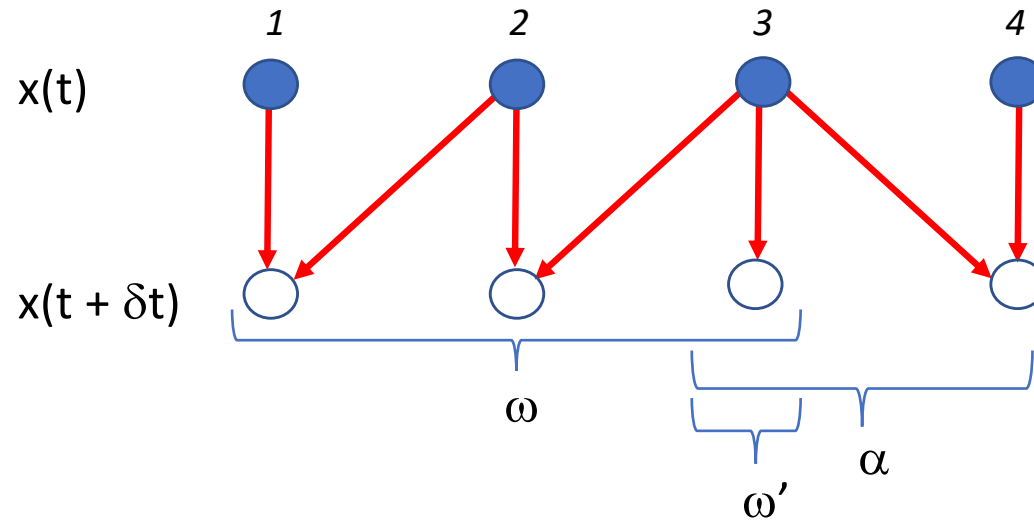


$$Q^i(\mathbf{x}) = \sum_{\mathbf{j}} \beta_{\mathbf{i}}^{\mathbf{k}(\mathbf{j})} [\mathbf{H}_{\mathbf{x}_r(\tau(\mathbf{j}))}(\mathbf{i}; \tau(\mathbf{j})) - \mathbf{H}_{\mathbf{x}_r(\tau(\mathbf{j}-1))}(\mathbf{i}; \tau(\mathbf{j}))]$$

- **Local heat flow** into community r during trajectory \mathbf{x} is

$$Q^r(\mathbf{x}) = \sum_{i \in r} Q^i(\mathbf{x}_r)$$

- N.b., heat flow into community r only depends on states of subsystems in r



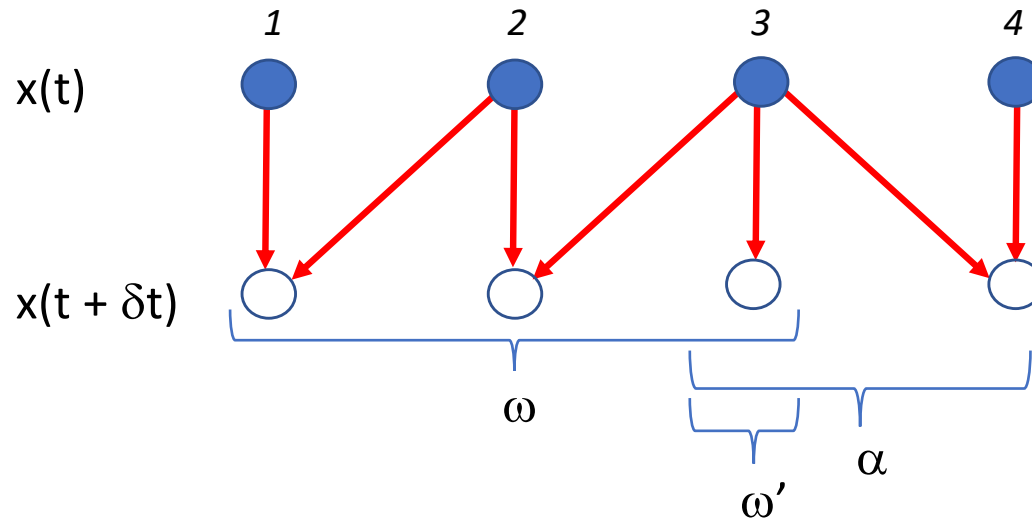
$$Q^r(\mathbf{x}) = \sum_{i \in r} Q^i(\mathbf{x}_r)$$

- **Local EP** of community r during trajectory \mathbf{x} is

$$\sigma^r(\mathbf{x}_r) = \Delta s^r(\mathbf{x}_r) - Q^r(\mathbf{x}_r)$$

- where as usual the **stochastic entropy** of community r during trajectory \mathbf{x} at time t is

$$s^r(\mathbf{x}_r(t)) = -\ln p_{\mathbf{x}_r(t)}(t)$$



- Let $R = \{r, r', \dots\}$ be a set of communities (not necessarily a full community structure)

- Define

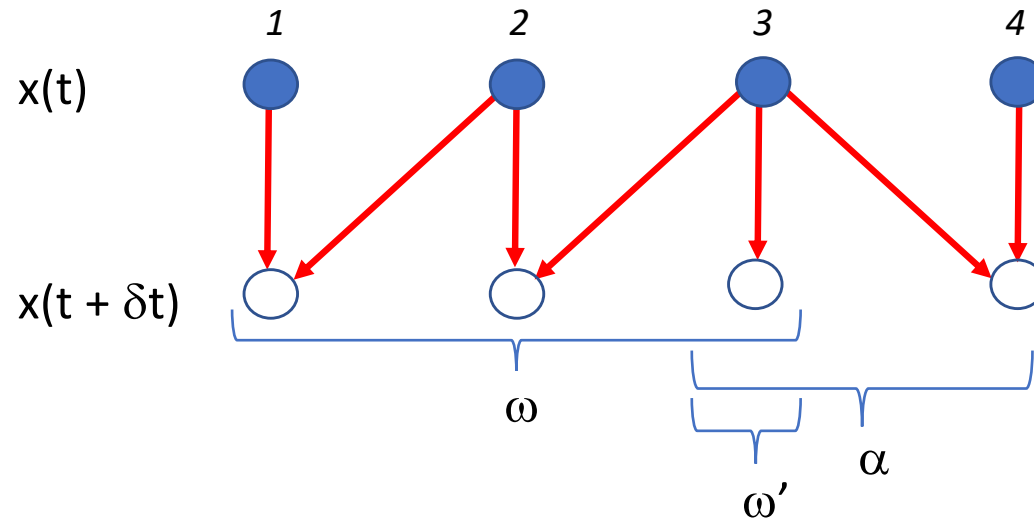
$$\vec{\sigma}^R(\mathbf{x}) = (\sigma^r(\mathbf{x}), \sigma^{r'}(\mathbf{x}), \dots)$$

$$\sigma^{\cup R}(\mathbf{x}) = \Delta s(\mathbf{x}_{r \cup r' \cup \dots}) - Q(\mathbf{x}_{r \cup r' \cup \dots})$$

- “**Vector-valued detailed fluctuation theorem**” (DFT):

$$\ln \left[\frac{\mathbf{P}(\vec{\sigma}^R)}{\tilde{\mathbf{P}}(-\vec{\sigma}^R)} \right] = \sigma^{\cup R}(\mathbf{x})$$

(with usual definition of $\tilde{\mathbf{P}}(-\vec{\sigma}^R)$ as probability under a reverse protocol)



- Let $R = \{r, r', \dots\}$ be a set of communities (not necessarily a full community structure)

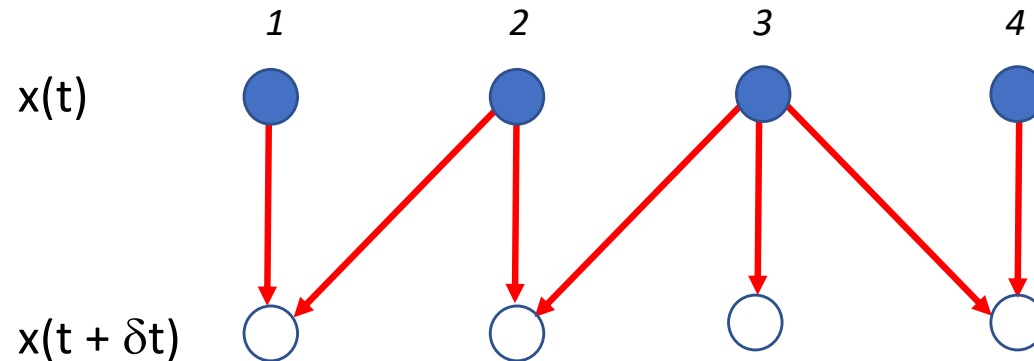
$$\ln \left[\frac{\mathbf{P}(\vec{\sigma}^R)}{\tilde{\mathbf{P}}(-\vec{\sigma}^R)} \right] = \sigma^{\cup R}(\mathbf{x})$$

- Subtract this DFT evaluated where R is a single community, r , from this DFT evaluated where R is a full community structure, to get a **conditional IFT**:

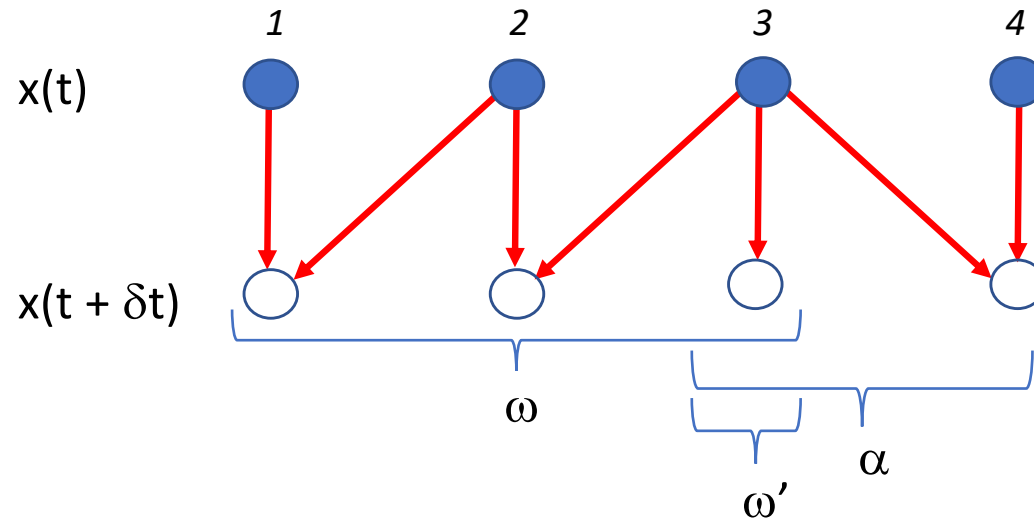
$$\langle e^{\sigma^r - \sigma} | \sigma^r \rangle = 1$$

where as before, σ is system-wide EP, and σ^r is EP of community r

This talk



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- 3) Resultant lower bounds on expected EP rate in terms of red arrow graph
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- For *any* community r , **system-wide EP** during trajectory \mathbf{x} is

$$\sigma(\mathbf{x}) = \sigma^r(\mathbf{x}) + \Delta s^{X_{-r}|X_r}(\mathbf{x}) - Q^{-r}(\mathbf{x})$$

where

- as before, local EP $\sigma^r(\mathbf{x}_r) = \Delta s^r(\mathbf{x}_r) - Q^r(\mathbf{x}_r)$
- $s^{X_{-r}|X_r}(\mathbf{x}(t)) = -\ln(p_{\mathbf{x}(t)}(t)) + \ln(p_{\mathbf{x}_r(t)}(t))$
- $Q^{-r}(\mathbf{x}) = \sum_{i \notin r} Q^i(\mathbf{x})$

$$\sigma(\mathbf{x}) = \sigma^r(\mathbf{x}) + \Delta s^{X_{-r}|X_r}(\mathbf{x}) - Q^{-r}(\mathbf{x})$$

- Take expectation value and differentiate:

$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$

$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$



- The *local EP rate* is $\langle \dot{\sigma}^r(t) \rangle$
 - This term is *non-negative*, and *concerns an entire community*
 - The term “ σ_X ” in (Sagawa and Shiraishi, PRE, 2015) can be negative, and does not concern an entire community
 - The term “ \dot{S}_i^X ” in (Horowitz and Esposito, PRX, 2014) is non-negative, but does not concern an entire community
 - The term “ σ_Ω ” in (Sagawa and Shiraishi, PRE, 2015) is non-negative, but concerns a subset of possible transitions of global system

$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$



$$\circ \quad \langle \dot{\sigma}_{-r}(t) \rangle = \sum_{x, x'} K_x^{x'}(-r; t) p_{x'}(t) \ln \left[\frac{K_x^{x'}(-r; t) p_{x'}(t)}{K_{x'}^x(-r; t) p_x(t)} \right]$$

is a *system-wide* EP rate

- just evaluated according to a *counterfactual rate matrix*, $K(-r; t) = \sum_{i \notin r} K(i; t)$

○ So this term *is non-negative*

$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$



$$\circ \quad \frac{d^r}{dt} S^{X|X_r}(t) = - \sum_{x, x'} K_x^{x'}(r; t) p_{x'}(t) \ln p_{x|x_r}(t)$$

is a derivative of conditional entropy, just according to a counterfactual rate matrix.

- By data-processing inequality, *if r is a community*, this term ***is non-negative***

$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$



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- By data-processing inequality, *if r is a community*, this term ***is non-negative***
- If:
 - 1) Two subsystems, where r is one of those subsystems
 - 2) r is a community, i.e., it evolves independently
 - 3) Full system is at an NESS

this term equals “learning rate” of (*Barato, Hartich, Seifert*, NJP, 2014)

$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$



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is a derivative of conditional entropy, just according to a counterfactual rate matrix.

- By data-processing inequality, *if r is a community*, this term ***is non-negative***
- If:
 - 1) Two subsystems, where r is one of those subsystems
 - 2) Don't require r to be a community – so lose guarantee of non-negative EP
 this term equals “information flow” of (Horowitz, Esposito, PRX, 2014). (See also (Sagawa, Ueda, NJP, 2013).)

$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$

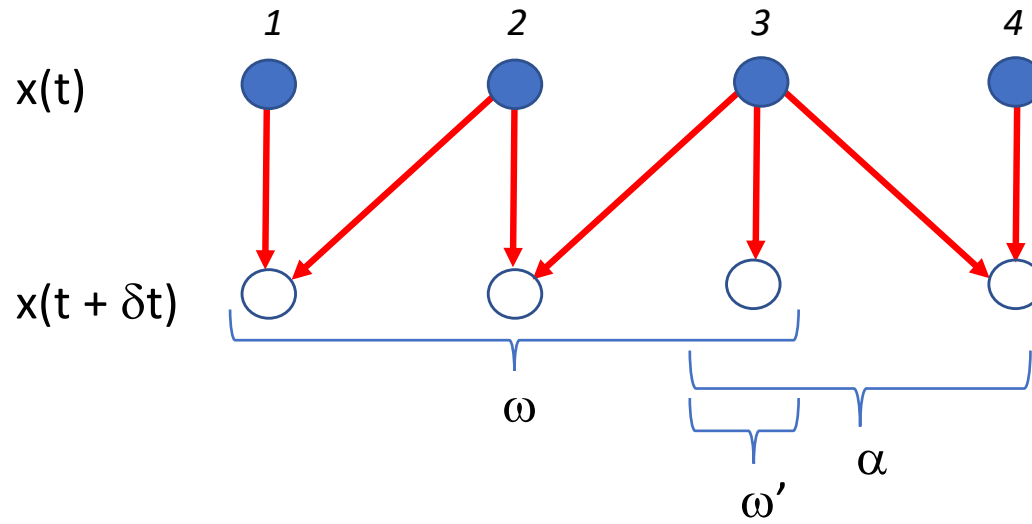


$$\frac{d^r}{dt} S^{X|X_r}(t) = - \sum_{x, x'} K_x^{x'}(r; t) p_{x'}(t) \ln p_{x|x_r}(t)$$

is a derivative of conditional entropy, just according to a counterfactual rate matrix.

- By data-processing inequality, this term *is non-negative*
- If:
 - 1) Two subsystems, where r is one of those subsystems
 - 2) Both systems are communities, i.e., they evolve independently
 - 3) One system never changes state

this term equals (time-derivative of) “Landauer loss” (Wolpert, Kolchinsky, NJP, 2020), aka “modularity dissipation” (Boyd, Mandal, Crutchfield, PRX, 2018)



- For any community r ,

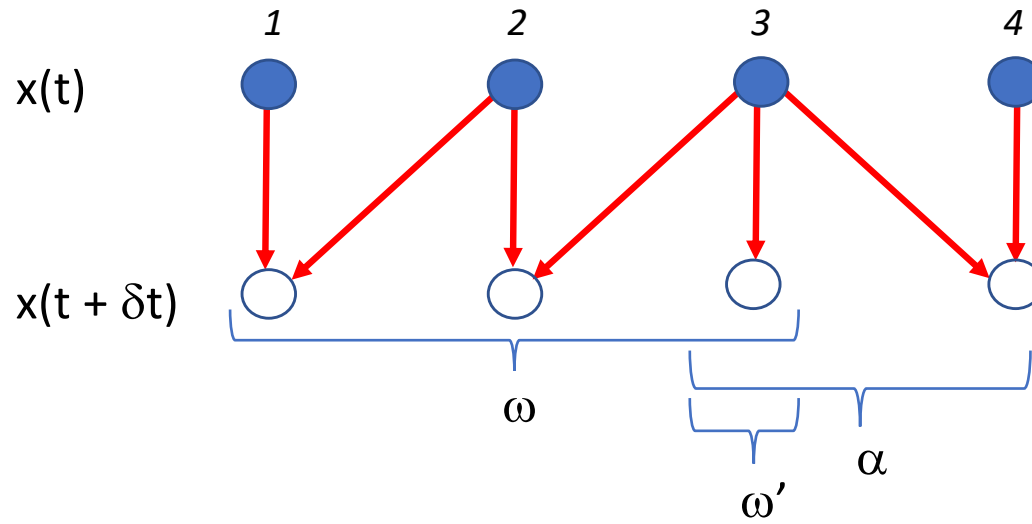
$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$

- All three terms on RHS are non-negative. So

$$\langle \dot{\sigma}(t) \rangle \geq \frac{d^r}{dt} S^{X|X_r}(t)$$

- Therefore in the example above,

$$\langle \dot{\sigma}(t) \rangle \geq \max \left[\frac{d^\omega}{dt} S^{X|X_\omega}(t), \frac{d^\alpha}{dt} S^{X|X_\alpha}(t), \frac{d^{\omega'}}{dt} S^{X|X_{\omega'}}(t) \right]$$



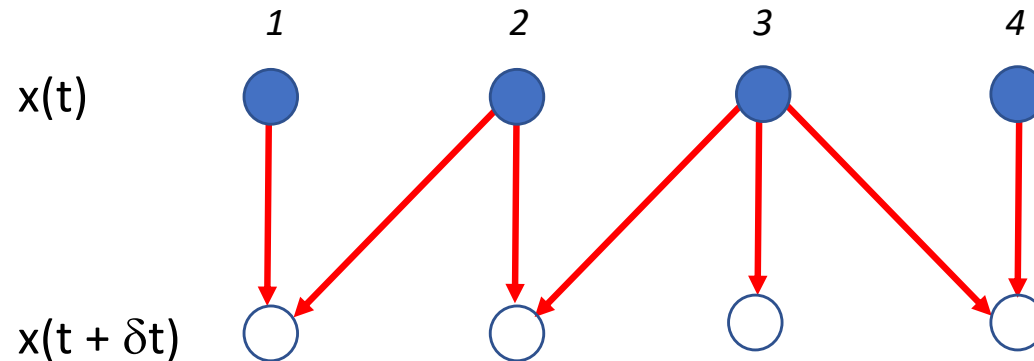
- For any community r ,

$$\langle \dot{\sigma}(t) \rangle = \langle \dot{\sigma}^r(t) \rangle + \langle \dot{\sigma}_{-r}(t) \rangle + \frac{d^r}{dt} S^{X|X_r}(t)$$

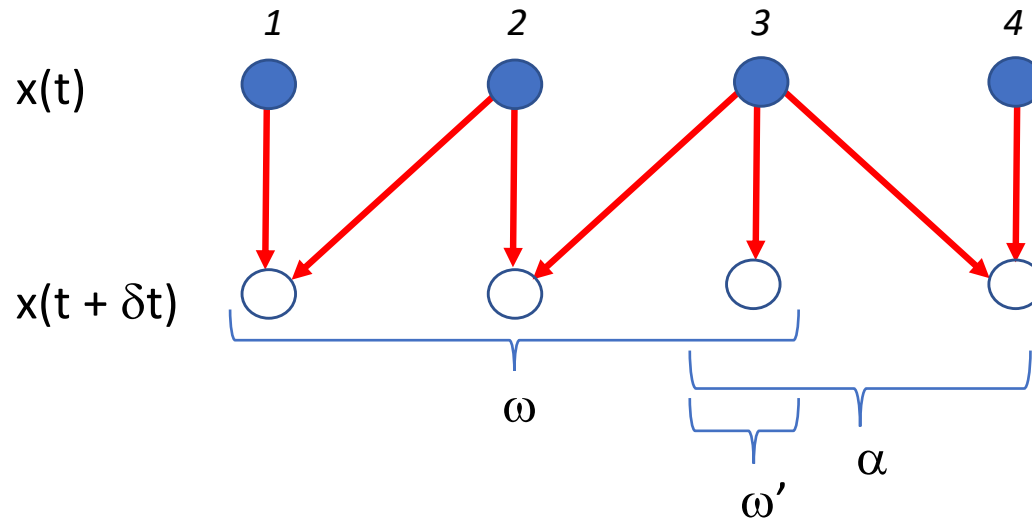
- In the example above, ω' is a community within ω .
- So can “iterate” the full decomposition of expected EP rate, by decomposing $\langle \dot{\sigma}^\omega(t) \rangle$
- Therefore in the example above,

$$\langle \dot{\sigma}(t) \rangle \geq \frac{d^\omega}{dt} S^{X|X_\omega}(t) + \frac{d^{\omega'}}{dt} S^{X_\omega|X_{\omega'}}(t)$$

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- **System-wide heat flow** during trajectory \mathbf{x} is

$$Q(\mathbf{x}) = \sum_i Q^i(\mathbf{x}) = \widehat{\sum}_r Q^r(\mathbf{x}_r)$$

where **inclusion-exclusion sum** (“in-ex sum”) is

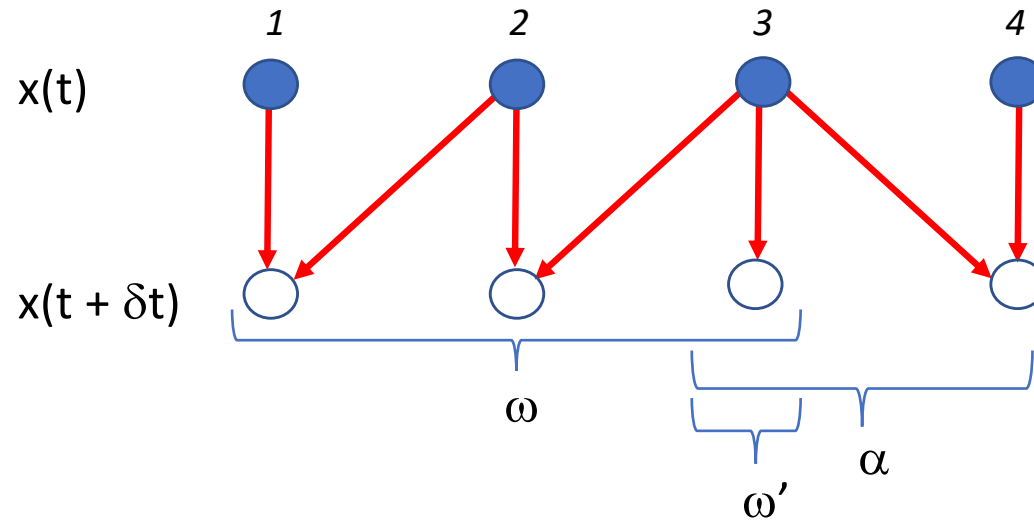
$$\widehat{\sum}_r Q^r(\mathbf{x}_r) = \sum_r Q^r(\mathbf{x}_r) - \sum_{r < r'} Q^{r \cap r'}(\mathbf{x}_r) + \dots$$

- Therefore **system-wide EP** during trajectory \mathbf{x} is

$$\sigma(\mathbf{x}) = \Delta s(\mathbf{x}) - Q(\mathbf{x}) = \widehat{\sum}_r \sigma^r(\mathbf{x}) - \Delta I^*(\mathbf{x})$$

where **in-ex information** is

$$I^*(\mathbf{x}(t)) = -s(\mathbf{x}(t)) + \widehat{\sum}_r s^r(\mathbf{x}(t))$$



- Conditional IFT:

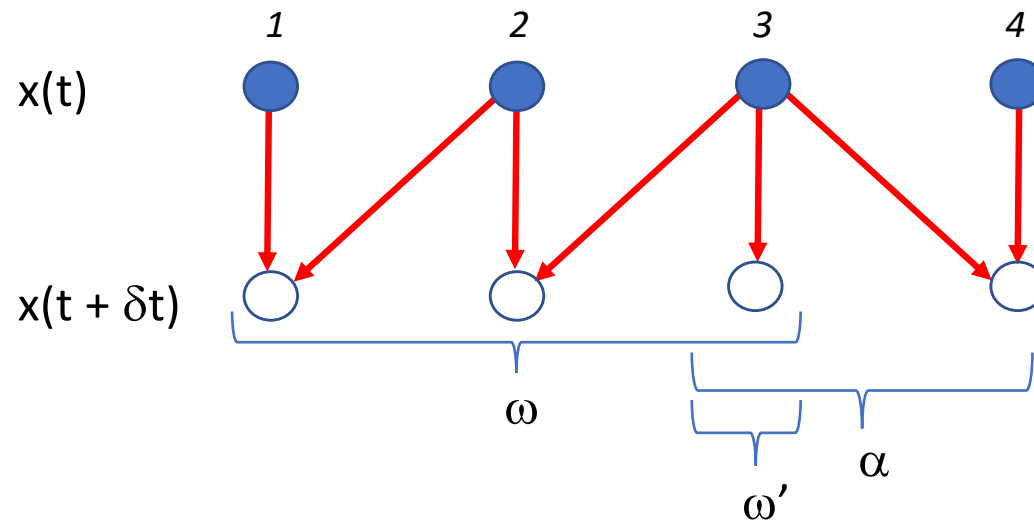
$$\langle e^{\sigma^r - \sigma} | \sigma^r \rangle = 1$$

- Second expansion of system-wide EP:

$$\sigma(\mathbf{x}) = \widehat{\sum_{r'}} \sigma^{r'}(\mathbf{x}) - \Delta I^*(\mathbf{x})$$

- Combining and applying Jensen's inequality shows that for any community r ,

$$\left\langle \widehat{\sum_{r'}} \sigma^{r'} - \Delta I^* \middle| \sigma^r \right\rangle \geq \sigma^r$$



$$\left\langle \widehat{\sum_{r'}} \sigma^{r'} - \Delta I^* \middle| \sigma^r \right\rangle \geq \sigma^r$$

Example (taking r = subsystems 3 and 4):

$$\langle \sigma^{123} - \sigma^3 + \sigma^{34} - \Delta_S^{1234} - \Delta_S^{123} + \Delta_S^3 - \Delta_S^{34} \mid \sigma^{34} \rangle \geq \sigma^{34}$$

CONCLUSIONS

- Restrictions on dependencies of each subsystem's rate matrix
- *Two system-wide decompositions of (trajectory-level) EP* in terms of those restrictions
- *Nonzero lower bounds on expected system-wide EP rate* in terms of those restrictions
 - Extends results on “*learning rate*”, “*Landauer loss*”, (and versions of “*second law for feedback control*”, “*second law for information processing*”, etc.)
- *Conditional fluctuation theorems*
 - If can observe EP of one subsystem, what is vector of EPs of other subsystems?
- Other lower bounds on expected EP rate, other conditional IFTs, etc.

arXiv:2003.11144, arXiv:2001.02205